

FROM INTENTION TO MOVEMENT: HIGH -PERFORMANCE COMMUNICATION PROTOCOL FOR NEURAL IMPLANTS.

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WIRELESS NEURAL IMPLANTS

1 | 5

MOTIVATION

- 17,000 new cases of Spinal Cord Injury every year
- Restore use of limb after spinal cord Injury

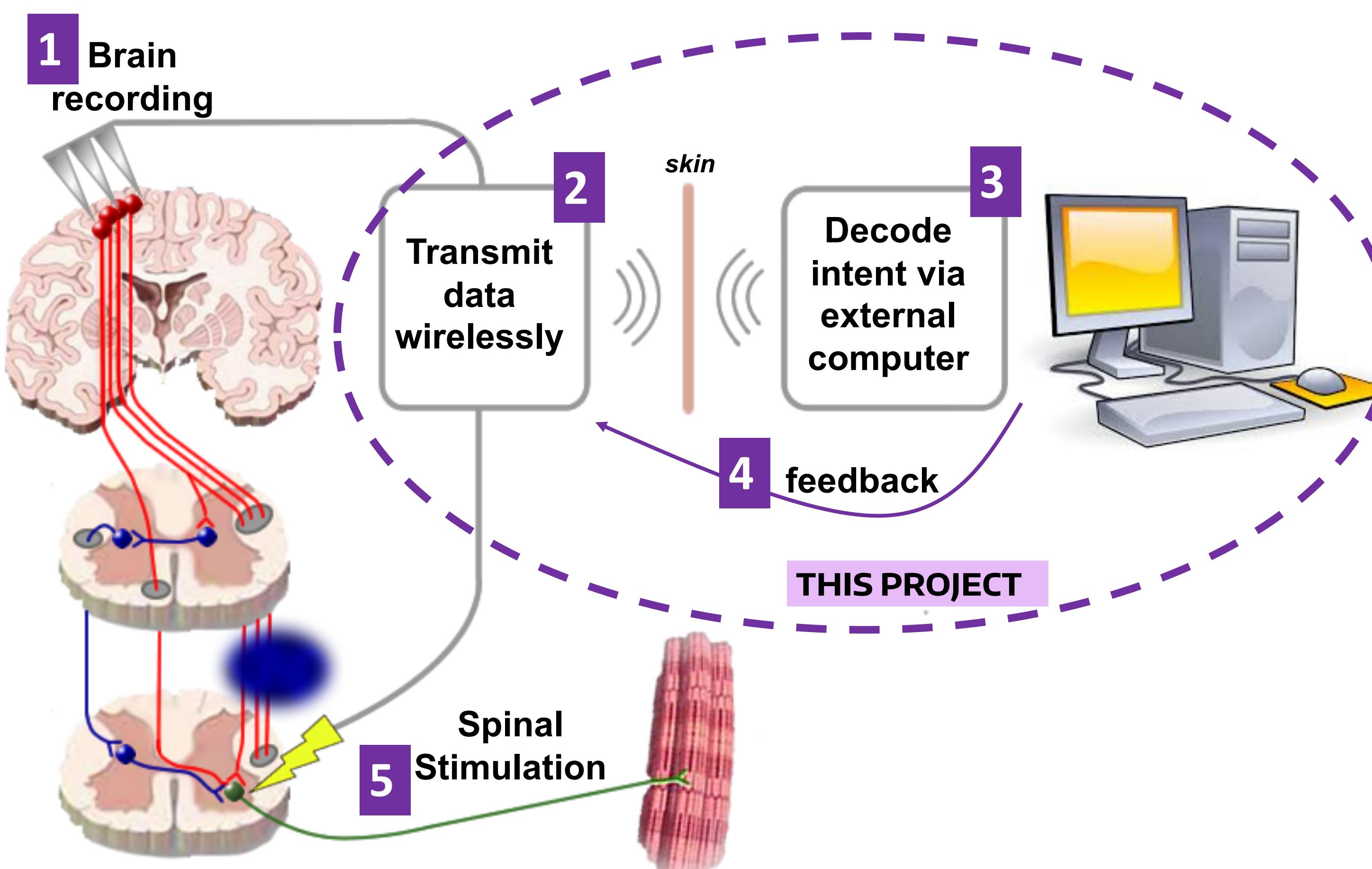
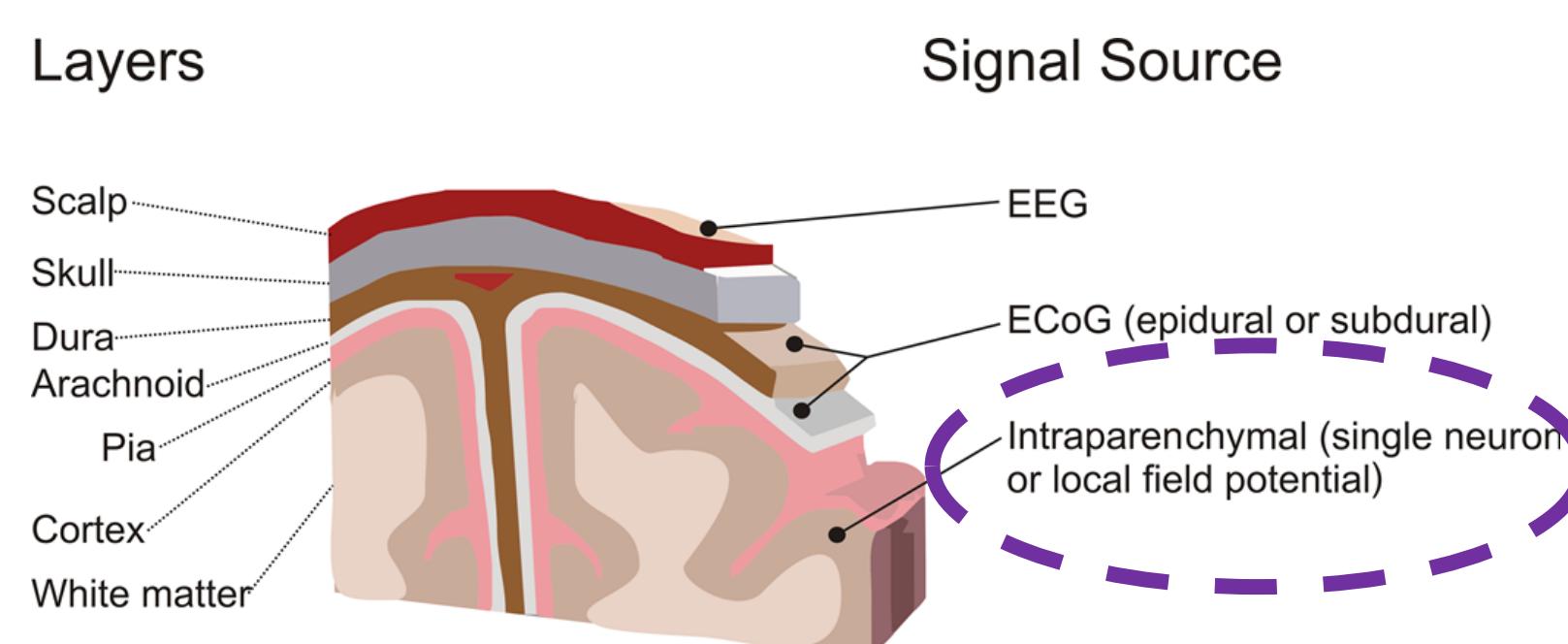


NeuralClip [1]
Vaishnavi Ranganathan



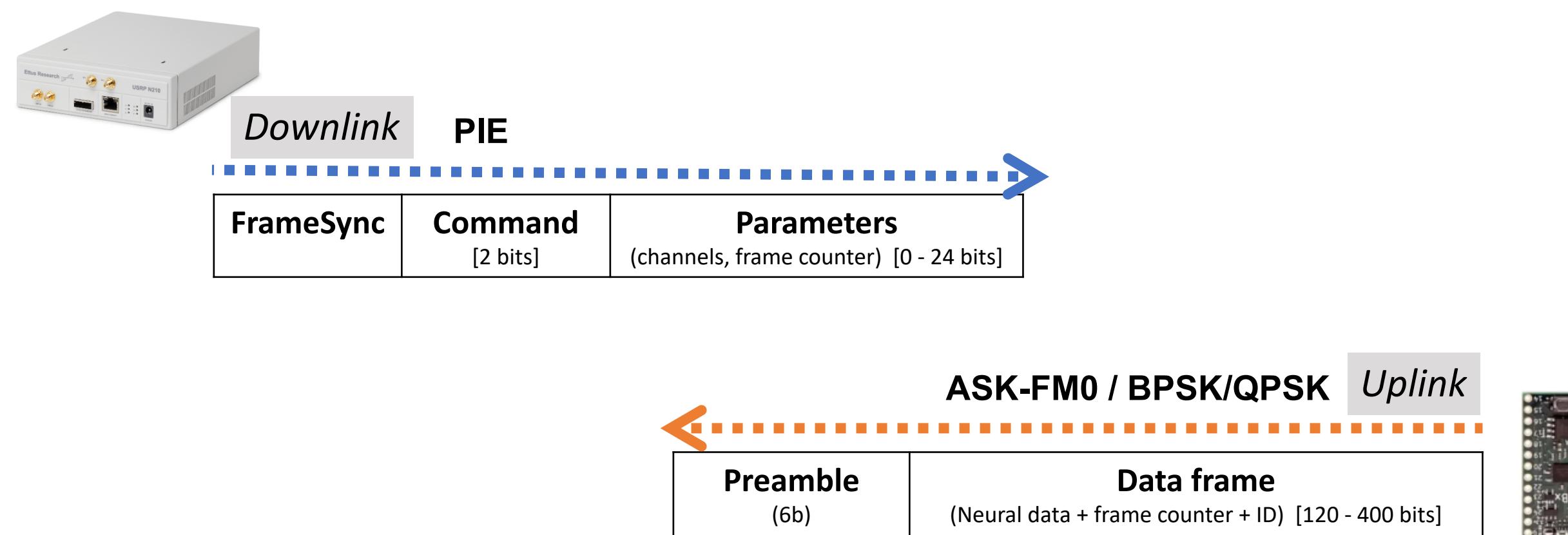
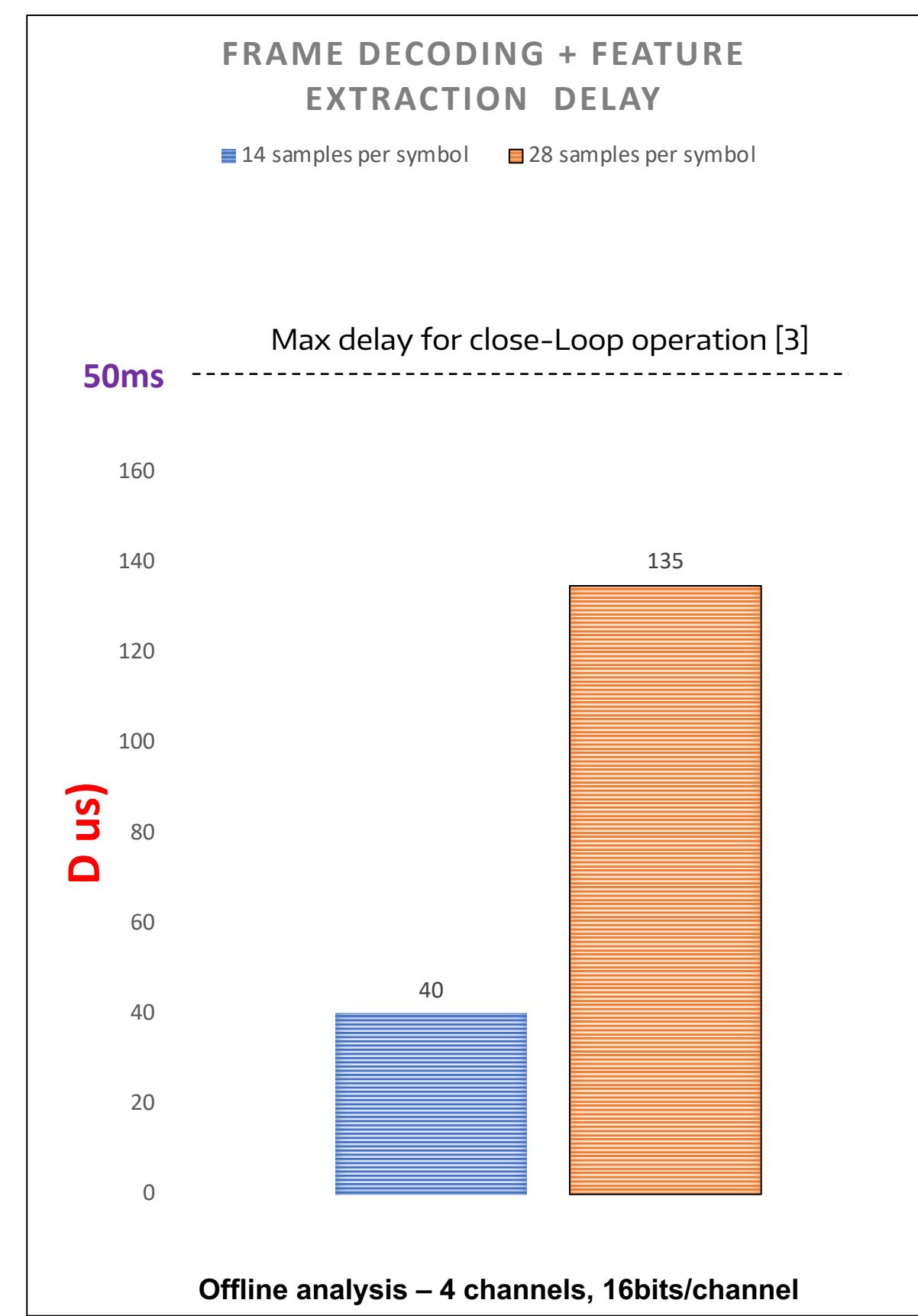
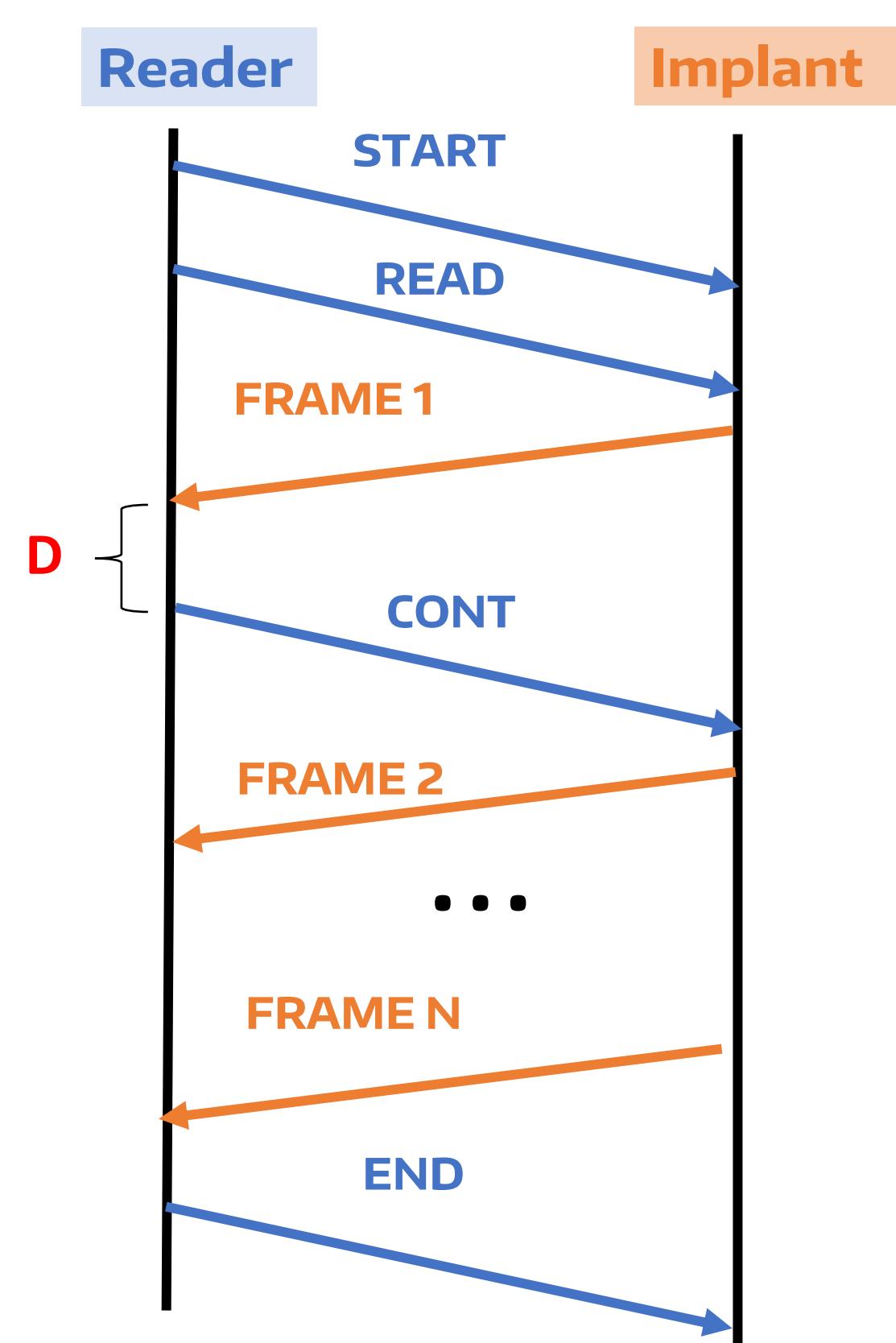
NeuralDisc [2]
James Rosenthal

- Computation: Low-Power FPGA
- High data rates (stream recorded signals)
- Low power consumption
- Neural chip: Intan RHS2116
 - 20 Hz to 1000 Hz
 - Multiple unipolar channels (N = 4 to 16)
 - 16 – N channels can be used for stimulation



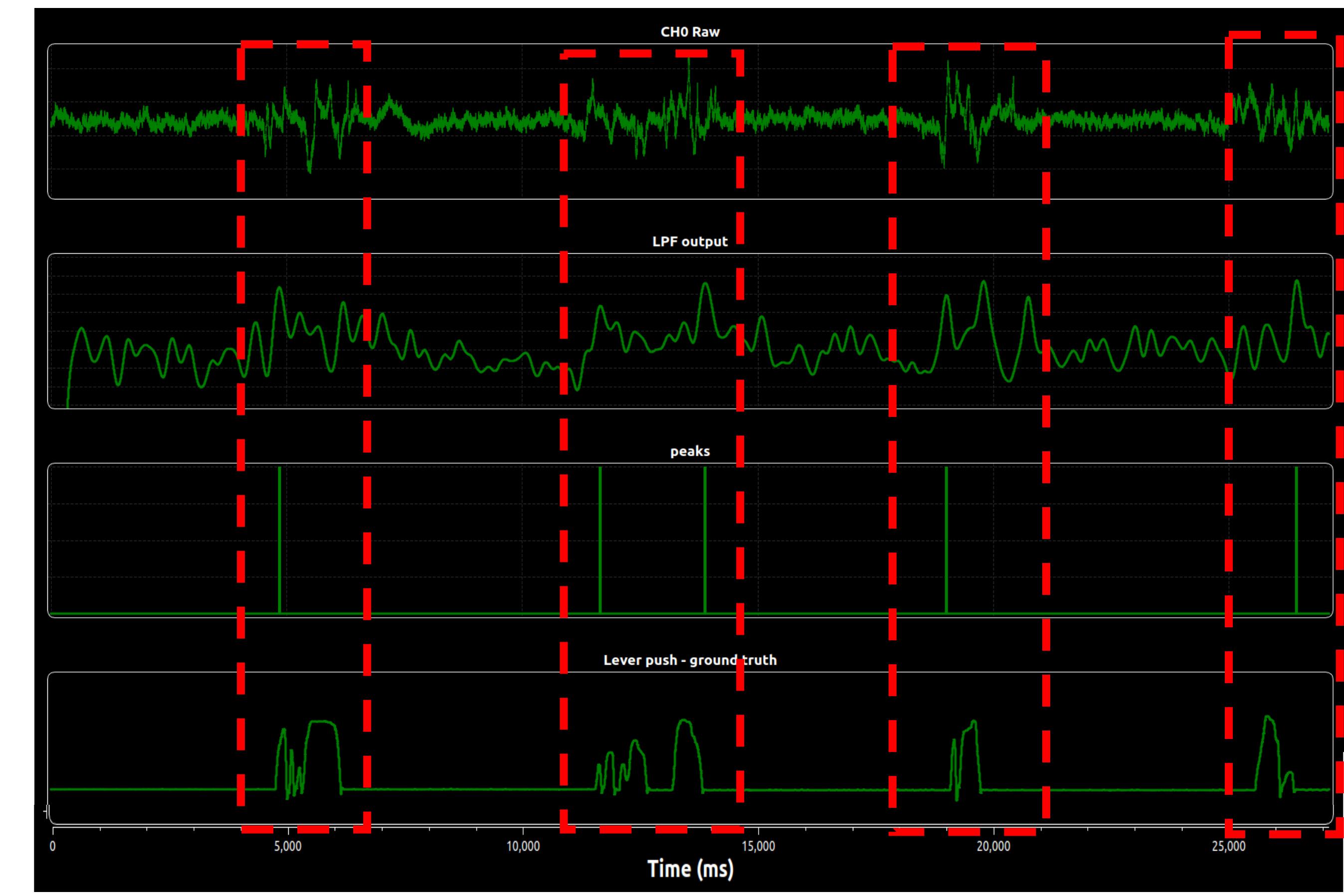
COMMUNICATION PROTOCOL

2



INTENTION DECODING

3 | 4



Future Work , Acknowledgments, References

Next steps

- Generalize: ASK, BPSK, DQPSK
- Tradeoff between implanted and external computation
- Real-time Feature Extraction with neural Implant (TinyFPGA)
- Privacy (cryptography?)



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Students: James Rosenthal, Anand Selvan

[1] V. Ranganathan et al., "NeuralCLIP: A Modular FPGA-Based Neural Interface for Closed-Loop Operation", IEEE/EMBS Conference on Neural Engineering (NER), 2019.

[2] J. Rosenthal, A. Sharma, E. Kampianakis, M.S. Reynolds, "A 25 Mbps, 12.4 pJ/bit DQPSK Backscatter Data Uplink for the NeuroDisc Brain Computer Interface" IEEE transactions on biomedical circuits and systems.

[3] A. Jackson, I. Mavoori, E.E. Fetz, "Long-term motor cortex plasticity induced by an electronic neural implant", Nature, vol. 444, 2006

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