

Enhancing Co-Adaptive Myoelectric Interfaces with Eye Tracking

CONTACT INFO

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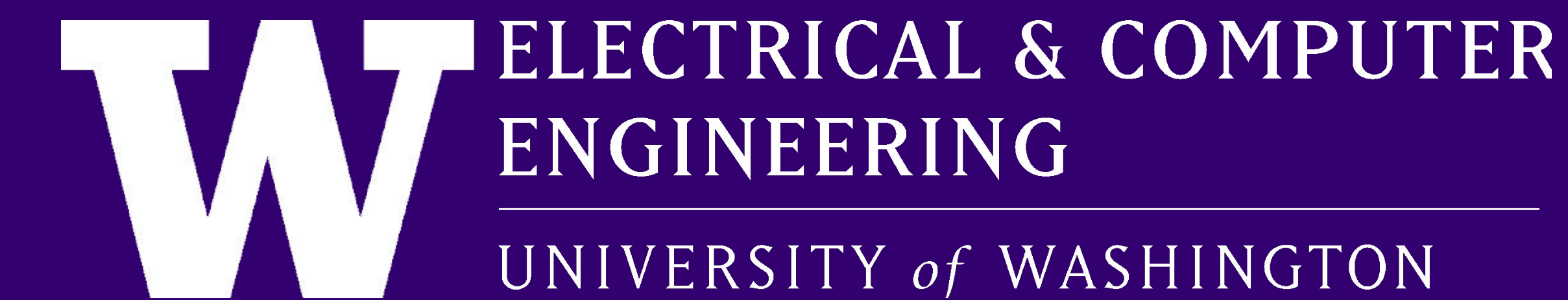
<https://amberhychou.github.io/>



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Introduction

PRIOR RESEARCH

- Adaptive decoders improve neural interface (NI) performance^{1,2}.
- Eye movements evolve as users learn sensory-motor mappings³.

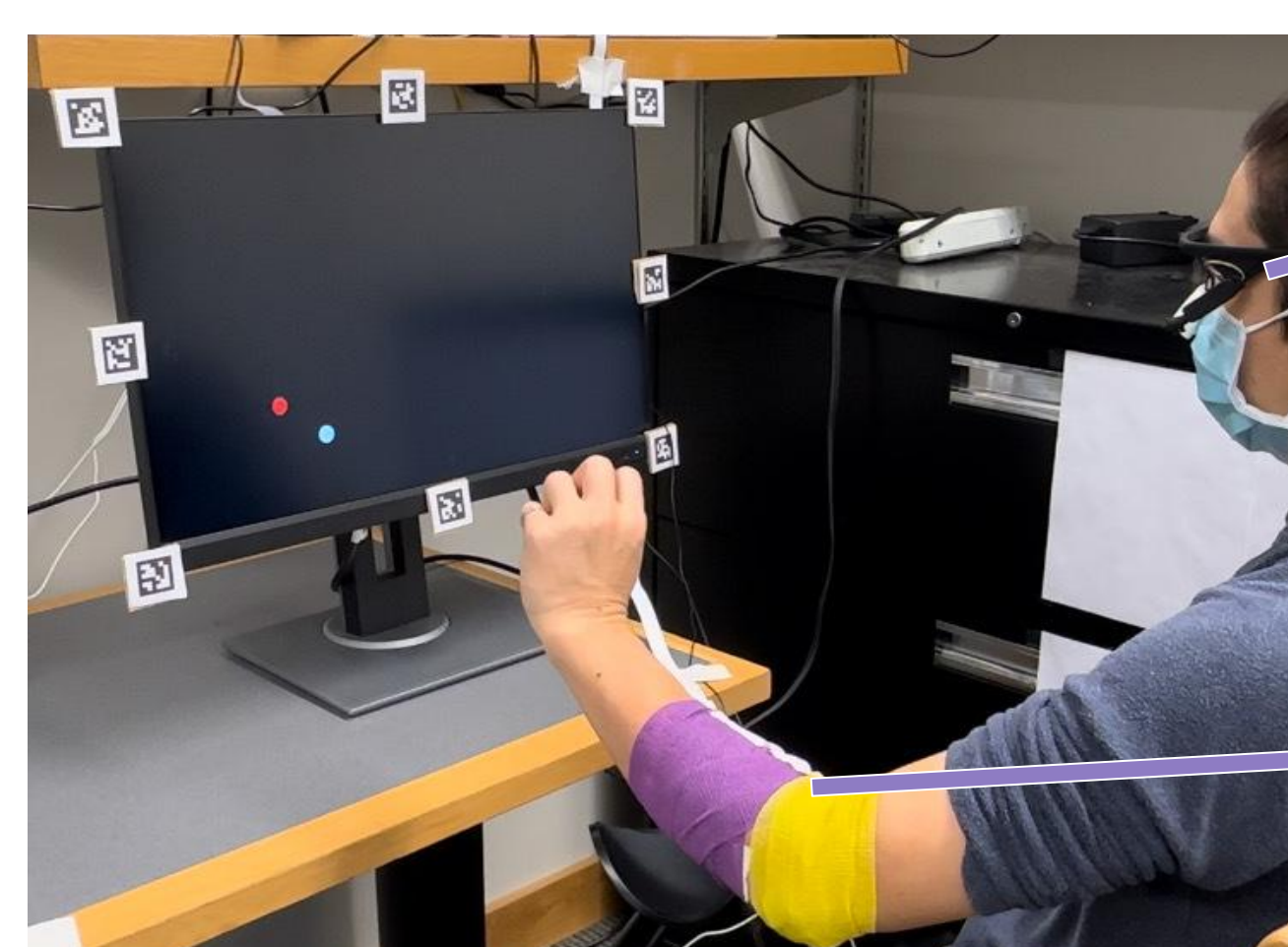
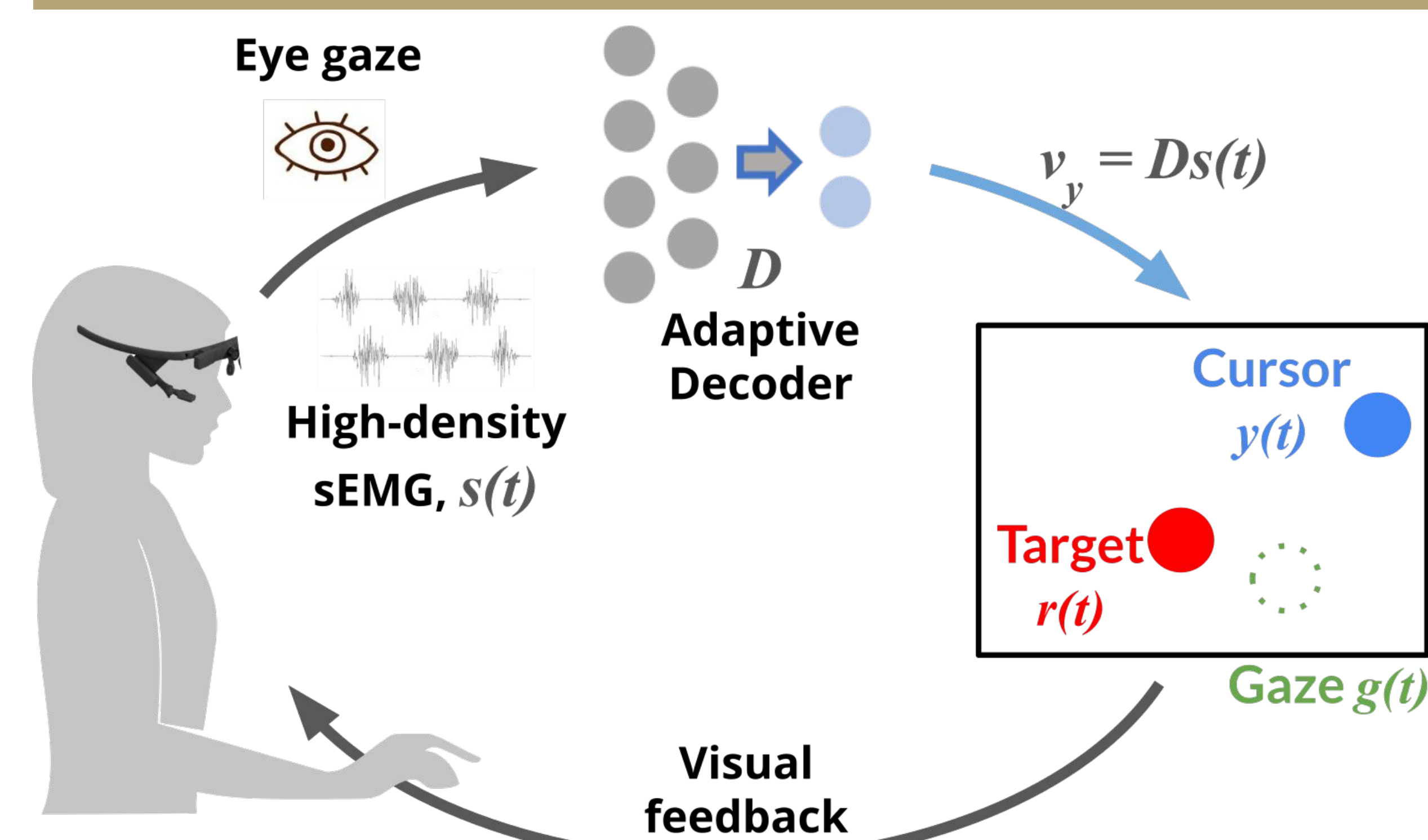
CHALLENGES/OPEN QUESTIONS

- Identify link between NI learning and eye movement.
- Current adaptive algorithms rely on structured tasks to train decoder, which limits user autonomy.

OUR GOALS

- Quantify relationship between user learning and eye movement to identify biomarkers of learning.
- Adapt interface based on eye movement biomarkers.

Co-Adaptive Myoelectric Interface



Eye-tracking headset

64-ch sEMG electrode

- Participants control cursor using forearm sEMG to follow a continuous moving target.
- Decoder D is adapted using gradient-based learning that minimizes **task error**:

$$\text{task error} = \|\dot{r} - \dot{y}\| - D \cdot s\|_2^2$$

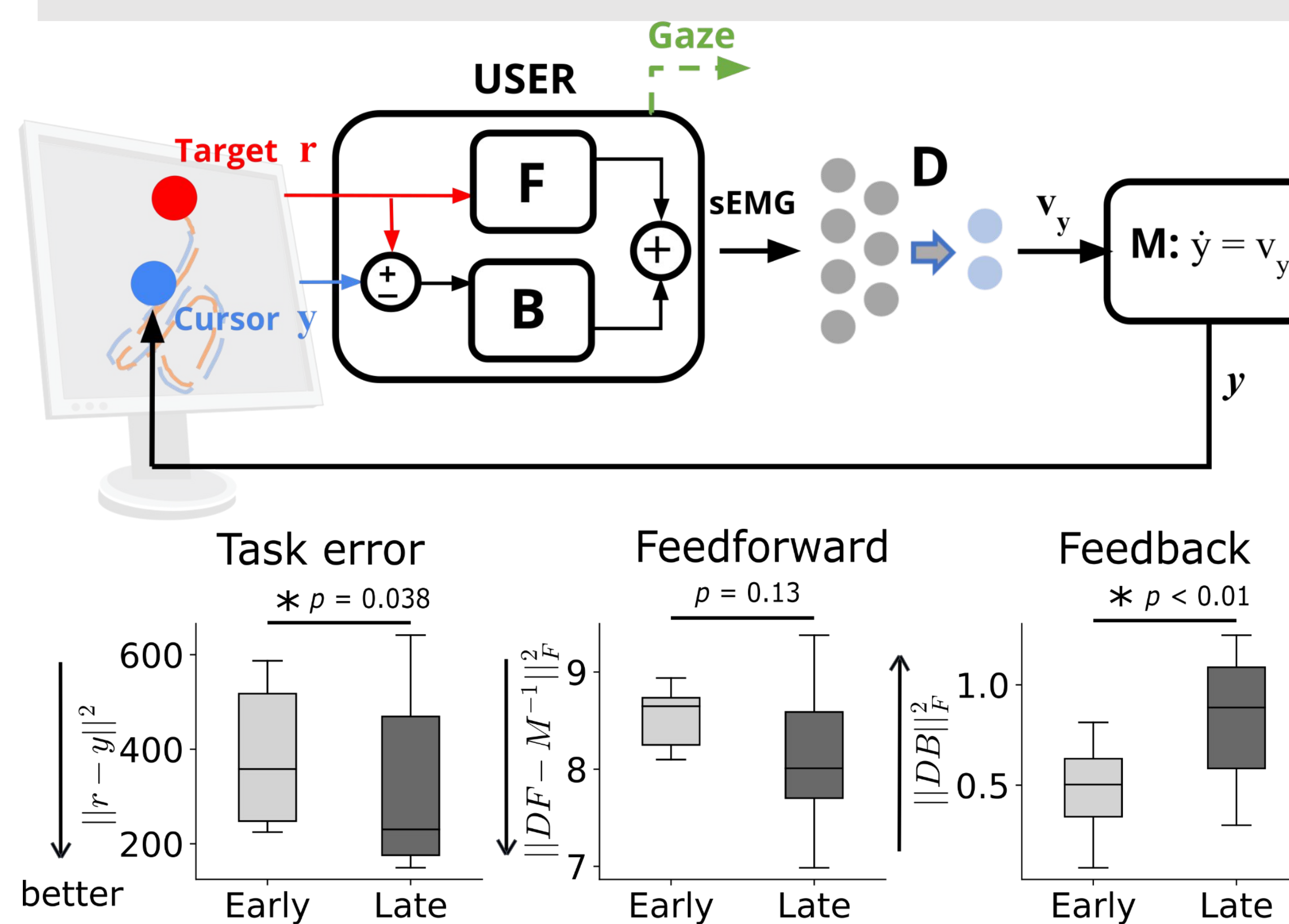
- In current methods^{1,2}, intended goal τ is the target.
- D is initialized randomly and updated iteratively using 20-second batches of data.

Experiment 1: eye gaze in interface learning

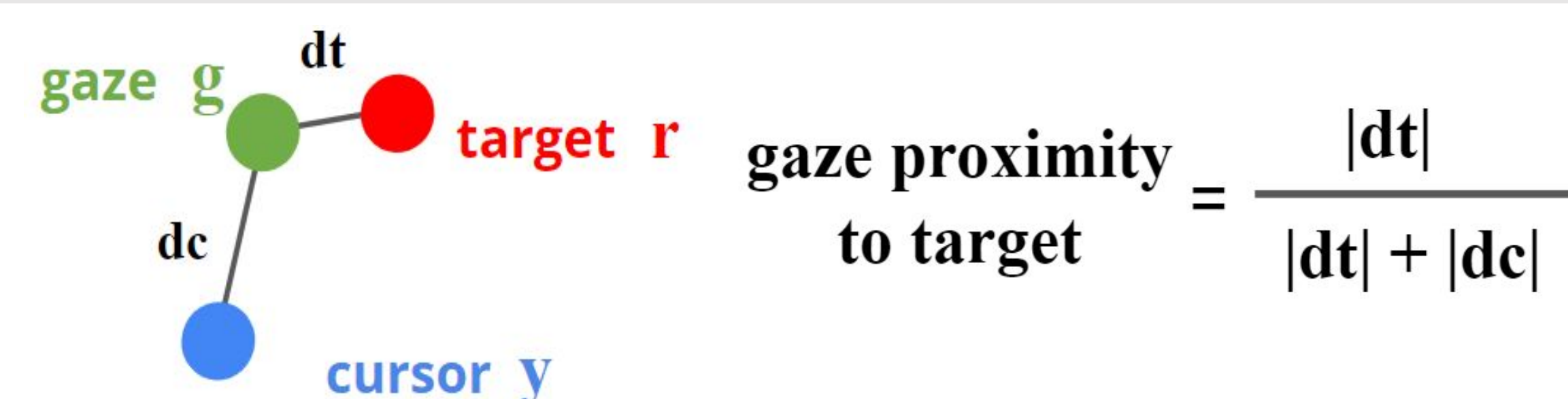
OBJECTIVE: Identify relationships between user learned controllers and gaze during adaptive myoelectric learning.

- Participants (N = 7) did tracking task with myoelectric interface.
- Eye gaze was measured during task operation.
- Each trial was 4-minute; total 12 trials.

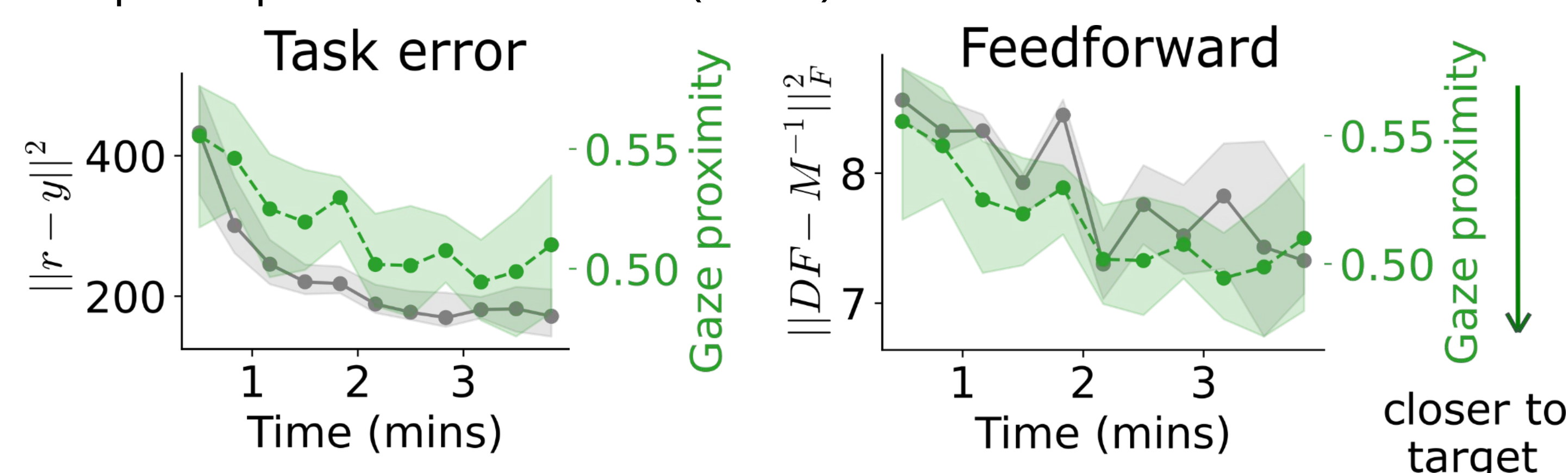
RESULT 1: Time-domain Task Performance, Frequency-domain Feedforward and Feedback⁴ Improved During Adaptation.



RESULT 2: Gaze Shifted Closer to the Target Compared to the Cursor as Performance and Feedforward Control Improves.



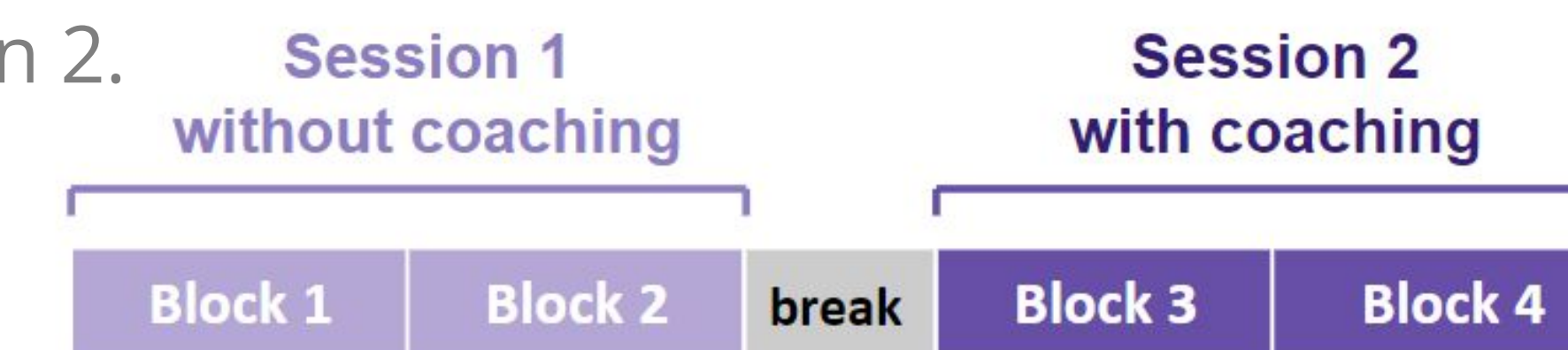
For participants who learned (N = 4):



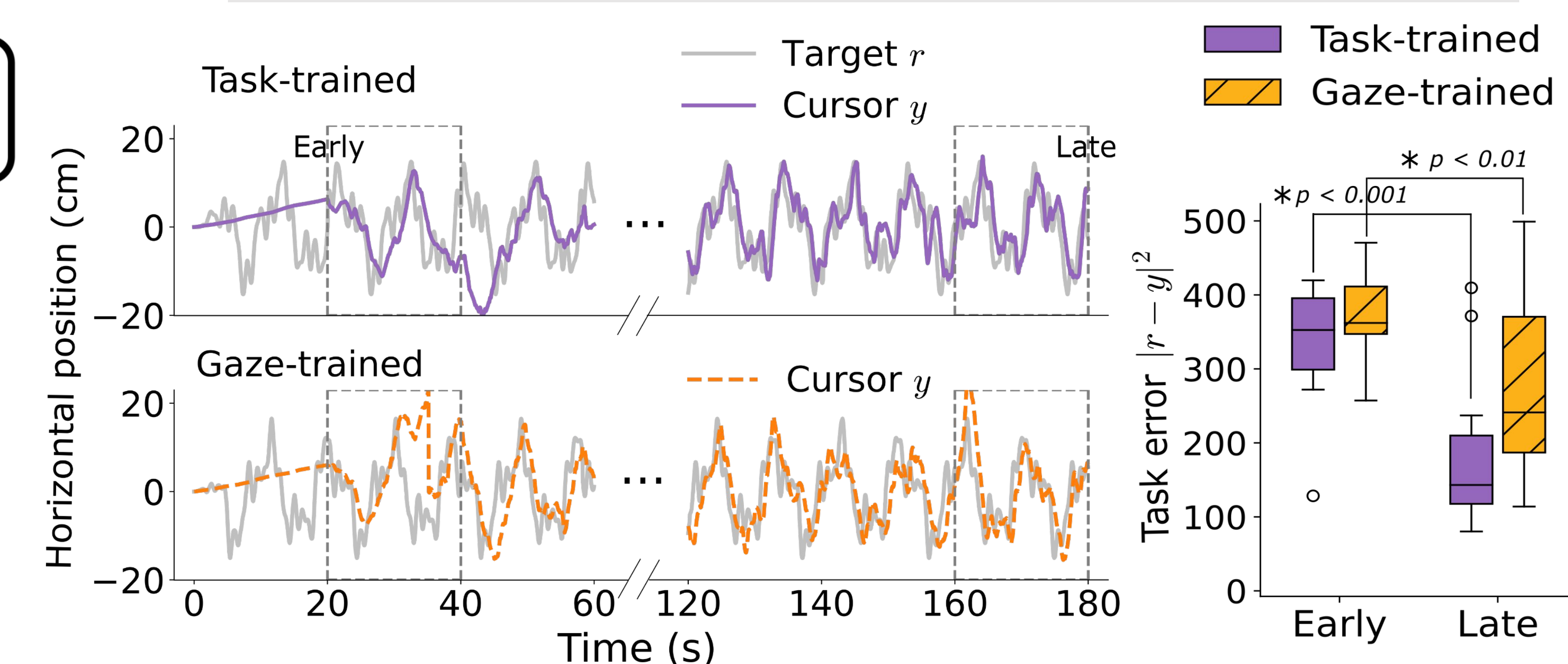
Experiment 2: using eye gaze to train decoder

OBJECTIVE: Adapt a myoelectric interface using eye gaze as training data.

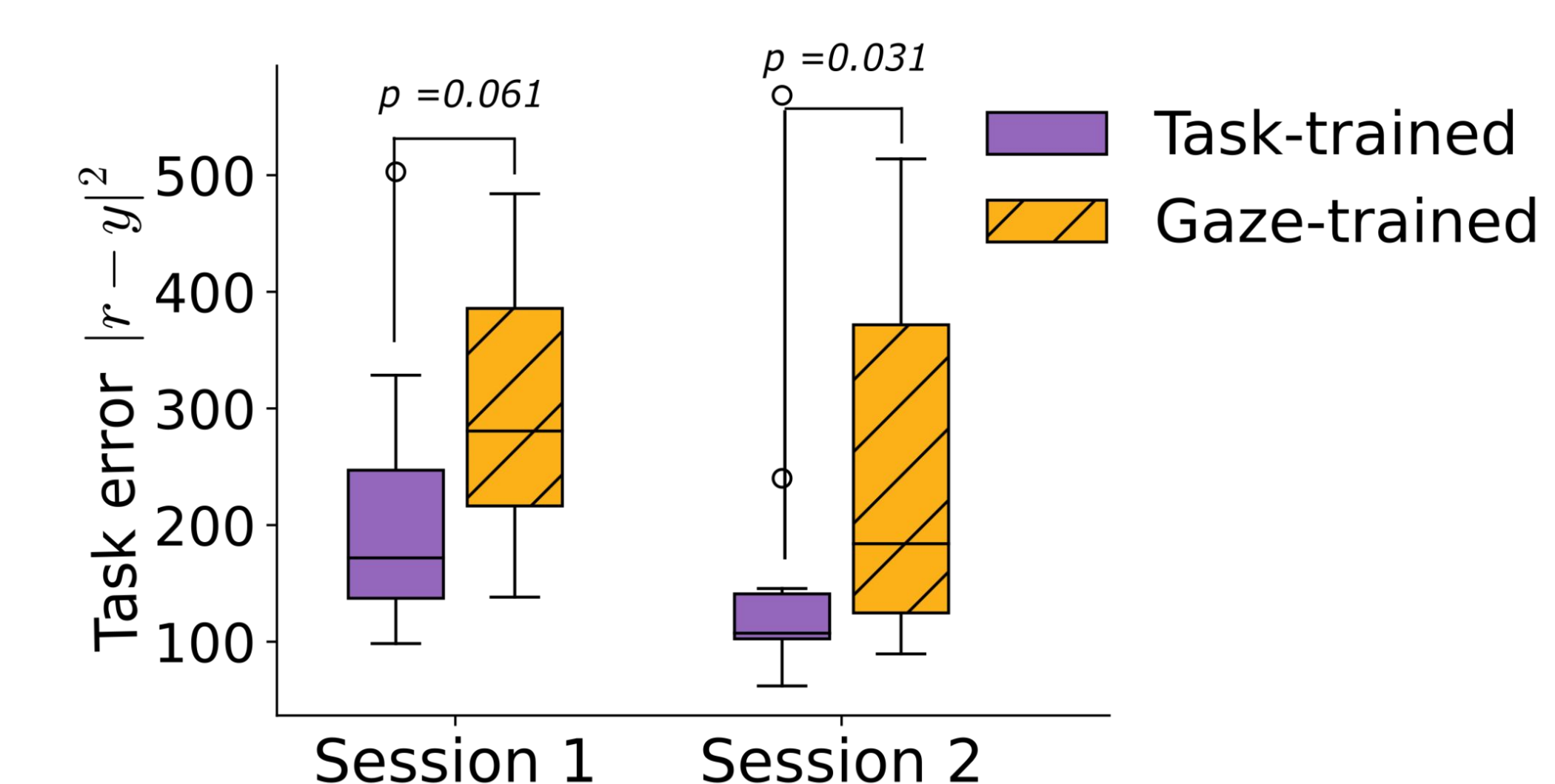
- Participants (N = 11) did tracking task with myoelectric interface trained on eye gaze. User intended goal τ is the gaze position.
- Users gazed on target in Session 2.
- Each trial was 3-min adaptive; total 12 trials.



RESULT 1: Time-domain Task Performance Improved for Both Gaze-Trained and Conventional Task-Trained Decoders



RESULT 2: Gaze-Trained Decoder Performed Comparably to Task-Trained Decoder; With & Without Fixation on Target.



Video Demo



Preprint



REFERENCES: [1] Orsborn et al. 2014. Closed-loop decoder adaptation shapes neural plasticity for skillful neuroprosthetic control. *Neuron*. [2] Madduri et al. 2022. Co-Adaptive Myoelectric Interface for Continuous Control. *IFAC-PapersOnLine*. [3] Sailer et al. 2005. Eye-Hand Coordination during Learning of a Novel Visuomotor Task. *J. Neurosci.* [4] Yamagami et al., 2021. Effect of Handedness on Learned Controllers and Sensorimotor Noise During Trajectory-Tracking. *IEEE Trans. on Cyber.*

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