

Enhancing GNSS Resilience with AI: Single-Frequency TEC Estimation Using the Portable SDR-Based ÆtherLink System Authors: Gokul Nathan, Aakash Namboodiri

Motivations



Rapid First Responders Robotics

Autonomy

High precision GPS enables new, innovative end-user applications

High Precision GPS Multi-Frequency GPS

Conventional GPS 15+ m

Challenges



When Signals travel through Earth's Ionosphere, they get delayed, refracted and attenuated -100+ mof errors

Strong signal interference can spoofing and jam (\bigcirc) 100+ mof errors



Hypothesis

Under moderate to severe **ionospheric dispersion**, a 1 TECU increase in slant TEC yields a measurable change in the differential signal characteristics of **L5 GPS's** In-phase (I) and Quadrature (Q) components—a variation that ÆTHER proposes to exploit via **ML augmented signal processing** to predict **satellite-specific TEC in real time**.

State of the Art

Current Methods	Measureme nt Type	Strengths	Current Limitations	How ÆTHERLink addresses it
Global vTEC Models [1-3]	Large-scale interpolation	Slobal coverage	Spatiotemporal resolution	In-situ measurements
		Low computational demands	SOnly 50% of RMSE error	Physics-based ML for high precision measurements
		Large-scale monitoring	Sexpensive and slow	SDRs + Embedded computers
Dual Frequency sTEC [3-5]	Frequency based measurement	High accuracy	Susceptible to cycle slips	Studies single frequency L5 GPS signals
			Highly susceptible to partial outages	
		Real time	Needs specialized equipment	Uses commonly available RF equipment
			High convergence times	Immediate measurements

References:

[1] - G. Johnston et al. Springer Handbook of Global Navigation Satellite Systems, 2017

[2] - H. Mahbuby and Y. Amerian. Pure Appl. Geophys., vol. 178, no. 4, Apr. 2021

[3] - P. Chen et al. Advances in Space Research, vol. 65, no. 1, Jan. 2020 [4] - Y. Yin et al. IEEE Transactions on Geoscience and Remote Sensing, vol. 62, 2024

[5] - M. Li et al. Space Weather, vol. 22, no. 7, Jul. 2024



ELECTRICAL & COMPUTER ENGINEERING UNIVERSITY of WASHINGTON



Ionospheric IQ Sampling Simulation BPSK Heat-map



Increasing In-Phase Corruption (I)

ION ML will train on patterns collected under known TEC conditions to predict per satellite sTEC along the line of sight.



Ellipticity of all plots and pattern support hypothesis that individual satellite's IQ values are affected differently.



Limitations

• Hardware Constraints The existing hardware has limited capabilities in terms of operation across different platforms, leading to potential incompatibility issues and performance bottlenecks.

• Software Compatibility Issues Although software solutions are available, they do not always integrate seamlessly with diverse hardware platforms, complicating deployment and scaling.

Existing algorithms, such as Phase-We are currently exploring Locked Loop (PLL), heavily rely on extensive filtering techniques. While alternative algorithms that minimize filtering to retain key this is useful for certain applications, signal features while can inadvertently eliminate important signal characteristics that may be maintaining tracking accuracy critical for more precise tracking and





Discussion



• Preliminary data suggest a combination algorithms with both conventional and ML components is good candidate for ION ML, though further studies need to conducted to validate this proposition





Future Works

Future Works addressing Limitations

• Preliminary Findings

This study is in its early stages, and further investigations are needed to validate and refine the results.

• Algorithm Limitations

We are currently conducting more studies in the field to verify and develop our methods

We are currently focusing on improving the compatibility between software and hardware to ensure smoother integration across different systems using a more generic python and MATLAB based method